



# Operation Manual

Product name

*Electric Actuator controller  
Gateway (GW) unit (CC-Link type)*

Model / Series

**LEC-GMJ2**



**SMC Corporation**

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# LEC Series/ Gateway unit

## 1. Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions are categorized into three groups, "Caution", "Warning" and "Danger" depending on the level of hazard and damage, and the degree of emergency. They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC), Japan Industrial Standards (JIS)\*1) and other safety regulations\*2).

\*1) ISO 4414: Pneumatic fluid power -- General rules relating to systems

ISO 4413: Hydraulic fluid power -- General rules relating to systems

IEC 60204-1: Safety of machinery -- Electrical equipment of machines (Part 1: General requirements)

ISO 10218-1992: Manipulating industrial robots -- Safety

JIS B 8370: Pneumatic fluid power -- General rules relating to systems

JIS B 8361: Hydraulic fluid power -- General rules relating to systems

JIS B 9960-1: Safety of machinery -- Electrical equipments of machines (Part 1: General requirements)

JIS B 8433-1993: Manipulating industrial robots -- Safety, etc./

\*2) Labor Safety and Sanitation Law, etc.



### Caution

Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.



### Warning

Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.



### Danger

Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

## Warning

### **(1) The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.**

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results.

The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product.

This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

### **(2) Only personnel with appropriate training should operate machinery and equipment.**

The product specified here may become unsafe if handled incorrectly.

The assembly, operation and maintenance of machines or equipment must be performed by an operator who is appropriately trained and experienced.

### **(3) Do not service or attempt to remove product and machinery/equipment until safety is confirmed.**

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent dropping of driven objects or run-away of machinery/equipment have been confirmed.

2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.

3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.



## Warning

**(4) Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.**

1. Conditions and environments outside of the given specifications, or use outdoors or in a location exposed to direct sunlight.
2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
3. An application which could have negative effects on people, property, or animals requiring special safety analysis.

Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation. Check the product regularly in order to confirm normal operation.



# LEC-G Series/Gateway unit

## Safety Instructions

### **Caution**

**The product is provided for use in manufacturing industries.**

The product herein described is basically provided for peaceful use in manufacturing industries.

If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

### **Limited warranty and Disclaimer/Compliance Requirements**

The product used is subject to the following “Limited warranty and Disclaimer” and “Compliance Requirements”.

Read and accept them before using the product.

#### **[Limited warranty and Disclaimer]**

**(1) The warranty period of the product is 1 year in service or within 1.5 years after the product is delivered.**

**Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.**

**(2) For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.**

**This limited warranty applies only to SMC product independently, and not to any other damage incurred due to the failure of the product.**

**(3) Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.**

#### **[Compliance Requirements]**

When the product is exported, strictly follow the laws required by the Ministry of Economy, Trade and Industry (Foreign Exchange and Foreign Trade Control Law).

## 2. Outlines of Product

### 2.1 Features

The gateway unit (GW unit, hereafter) is the unit to connect the electric actuator controller(LEC series) to CC-Link. One unit can control up to 12 same type of controllers.

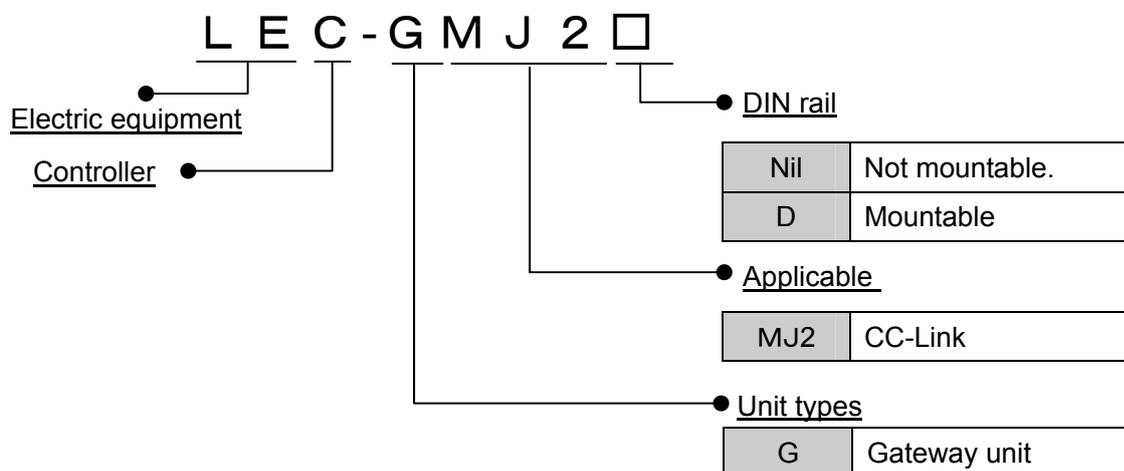
#### Caution

When setting up the device or when failure occurs, please refer to the operation manual of the controller, the actuator, and the teaching box as well as this operation manual.

\* Keep this operation manual accessible so it can be referred to when necessary.

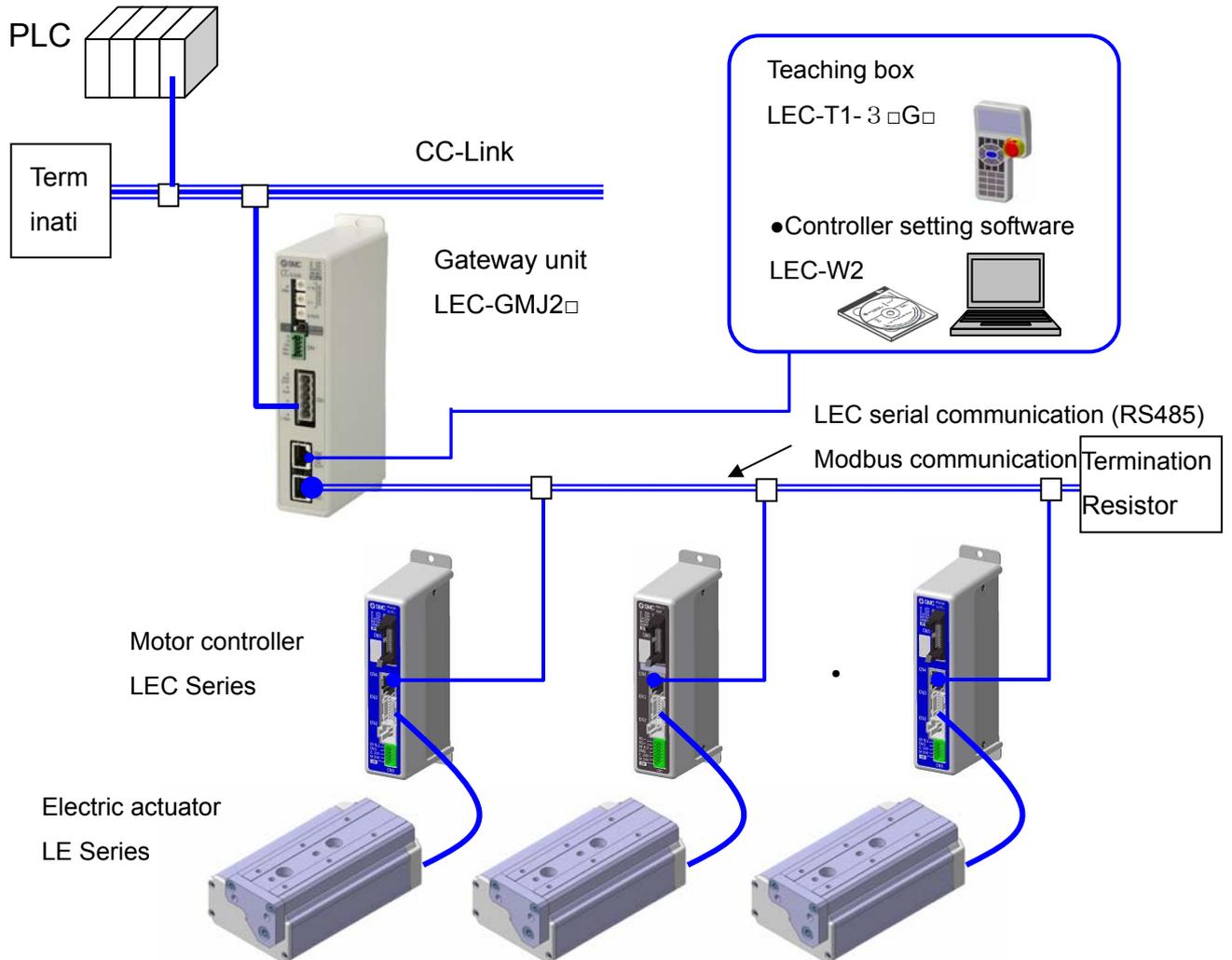
### 2.2 How to Order

How to order is shown below.



## 2.3 Structure of the product

The system applies this unit consists of the unit below.  
System structure drawing.



## 2. 4 Procedure (How to start the actuator)

Install, wire, set and operate the gateway unit referring to the procedure below when the product is used for the first time.

### (1) Checking the content of the package

After unpacking, check the description of the label to identify the gateway unit and the quantity of accessories.

Part's name	Quantity
Gateway unit (LEC – GMJ2)	1 pc.
Power supply connector	1 pc.

Gateway unit



Power supply connector



(\*)These items are included if you ordered by the part number for a set of controller and actuator.

### (2) Mounting the unit

Refer to **3.4 How to install** for the mounting of the gateway unit.

### (3) Initial setting of the connect controller

The parameters of the controller's that are is connected to the gateway unit need to be set.

Refer to section **4. 3 Setting of controller (LEC)**

### (4) Setting the unit

It is necessary to set the node address and the communication speed by the rotary switch of the gateway unit. Refer to section **4. Initial Setting**

### (5) Unit wiring / Connection

Connect cables to the connectors(CN1 to CN3) of the gateway unit.

Refer to section **5. External connection** for the wiring of connectors.



Connector

## (6) Power supply

Supply power 24V DC.

### **Caution**

Supply power first to the controller (LEC), then to the gateway unit.

If power is supplied to the gateway unit and then to the controller (LEC), reset the data link after supplying power to the controller (LEC).

(Refer to **12.4 Gateway unit control flag** for the details of data link reset.)

If the condition is normal, LED on the front of the gateway unit turns on as the table below when power is supplied.

Functions	LED condition	Condition
PWR	Green On	Supply of power
CN2 STAT	Off	CN2 (TB/PC terminal) invalid
BUS STAT	Green flashing	Controller IF is communicating
ALM	Green flashing	No alarm
L ERR	Off	CC-Link status normal
L RUN	Green On	CC-Link status normal

Refer to **10. LED display** for the explanation of LED lamps.

If LED [ALM] on the front panel of the gateway unit shows red, an alarm conditions has occurred.

## (7) Operation

Refer to **12. Memory map** for the assignment of the memory. Read the operation manual of LEC series as well.

### 3. Specifications

#### 3. 1 Specifications

Basic specifications of the product.

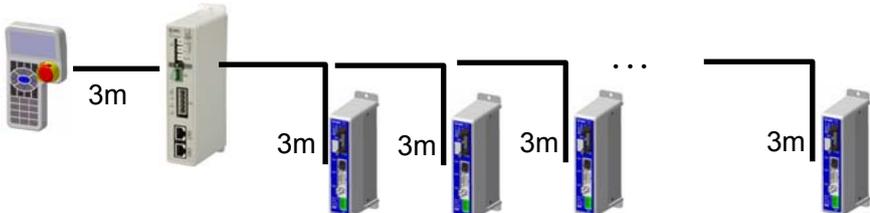
Item	Specifications
Rated voltage	24 VDC±10%
Current consumption	200mA or less (When teaching box is not connected) 300mA or less (When teaching box is connected)
Applicable controller	Electric actuator controller (LEC series)
Product to be connected	Max. 12pcs.

When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

【CC-Link type】

Item	Specifications					
Fieldbus	CC-Link Version 2.0					
Station type	Remote device station					
Occupied number of stations	4 stations extended cyclic 8 times (Input 896 point 108word / Output 896 point 108word)					
Communication speed	156k/625k/2.5M/5M/10Mbps					
Communication method	Broadcast Polling System					
Synchronization system	Frame synchronous communication					
Encoding method	NRZI					
Transmission system	Bus system (EIA RS485 compliant)					
Communication format	HDLC compliant					
Error control system	CRC( $X^{16}+X^{12}+X^5+1$ )					
Applicable communication cable	CC-Link cable					
Maximum length of cable	Communication speed (bps)	156k	625k	2.5M	5M	10M
	Total cable length (m)	1200	900	400	160	100

【Controller IF communication spec.】

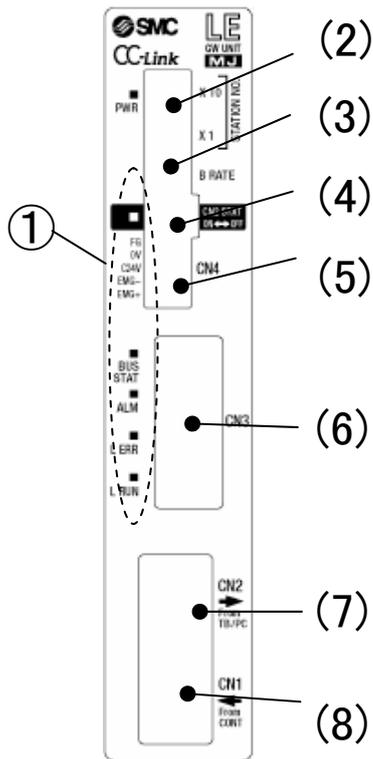
Item	Specifications
Serial communication	RS485 (Modbus protocol compliant)
Communication speed	115.2k or 230.4kbps (Select 115.2kbps when the teaching box is connected)
Cable length	<p>The total of the length of the line is assumed to be 36m or less. (3m×12)</p> <p>The trunk line and the branch line are contained.</p> 

【Conditions of environment】

Item	Specifications
Applicable ambient temperature	0~40°C(No freezing)
Applicable ambient humidity	90%RH or less (No condensation)
Atmosphere	No corrosive gas, flammable gas, oil mist, or particles.
Storage temperature	-10~60°C(No freezing)
Storage humidity	90%RH or less (No condensation)
Vibration	4.9m/s <sup>2</sup> (0.5G) or less
Enclosure	IP20
Mass	200g (screw mount type) 220g (DIN rail mount type)

### 3. 2 Details of parts

Details of parts of the gateway unit



No.	Display	Description	Detail
1	-	LED lamp	LED to indicate the condition of the gateway unit
2	STATION No.	STATION No.	Switch for setting address X1 and X10
3	B RATE	Communication speed	The switch to set the communication speed of the controller IF communication line.
4	CN2 SW	Communication switch	Disables the communication with the controller IF communication line, and ables the communication with the equipment which are connected to CN2.
5	CN4	Power supply connector	Connect the power supply and EMG signal.
6	CN3	Bus connector	Connect CC-Link line.
7	CN2	TB/PC connector	The connector which connect LEC teaching box (LEC-T1) or the ACT software Controller for setting (LEC-W2)
8	CN1	CONT connector	The connector for the controller IF communication line. Connect the motor controller (LEC series).



### 3.4 How to install

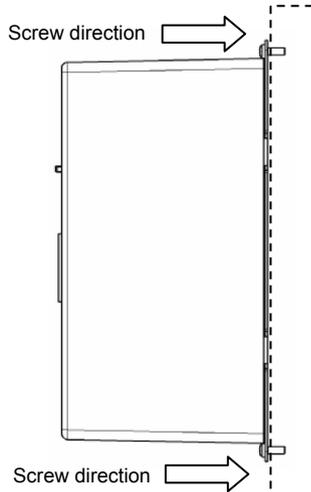
#### (1) How to install

There are two types of controllers; screw mount type and DIN rail mount type.

The followings are the descriptions on how to install each type:

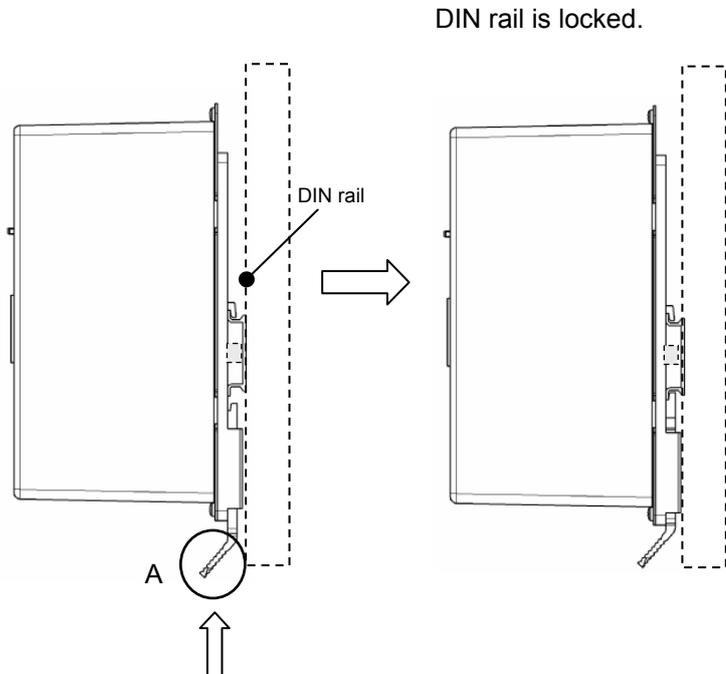
##### [1] Screw mount type (LEC-GMJ2)

(Installation with two M4 screws)



##### [2] DIN rail mount type (LEC-GMJ2D)

(Installation with the DIN rail)



Hook the controller on the DIN rail and press the lever of section A in the arrow direction to lock it.

#### (2) Installation location

Please install this gateway unit at an appropriate place where the surrounding temperature will not exceed 40°C.

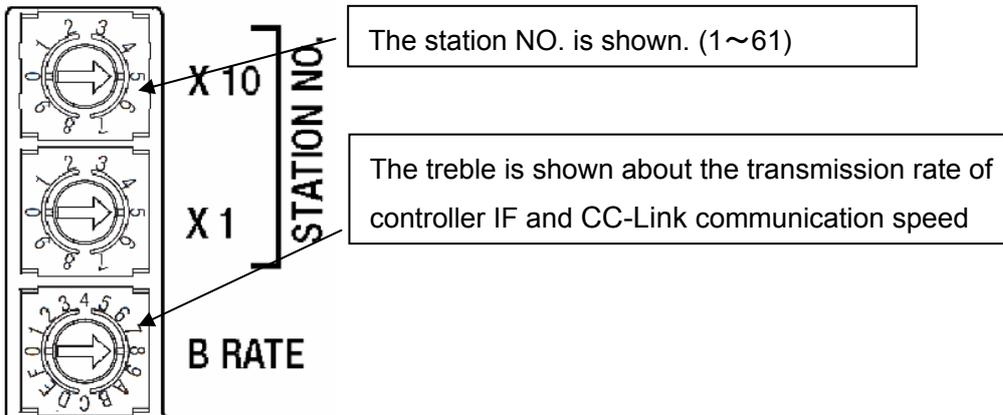
#### **Caution**

Install the gateway unit on a flat surface. Excessive pressure applied to the housing will damage the gateway unit.

## 4. Initial Setting

### 4.1 Gateway unit Communication speed switch (STATION NO.,B RATE)

Set the station number of the gateway unit and the transmission rate of the motor controller LEC and the CC-Link communication speed. The table below shows functions of switches.



#### ● STATION NO

Switch name	Set range	Description
STATION No (X10)	1~64	Set upper bits of the station. (Set value x 10)
STATION No (X1)		Set lower bits of the station. (Set value x 1)

#### ● B RATE switch

B RATE	The transmission rate of controller IF	CC-Link communication speed
F : D	Do not use	
C	230.4kbps	10Mbps
B		5Mbps
A		2.5Mbps
9		625kbps
8		156kbps
7 : 5	Do not use	
4	115.2kbps	10Mbps
3		5Mbps
2		2.5Mbps
1		625kbps
0		156kbps

※ Do not set B RATE to the value of "Unused"

Caution1: Set the controller IF communication speed at 115.2kbps to use the teaching box (LEC-T1-□).

Caution 2: Turn off the power supply in order to change the switch setting.

## **4. 2 Setting the switch to change the communication (CN2SW)**

Turn ON the communication switch (CN2SW) during CC-Link control. If the communication switch (CN2SW) is turned off during CC-Link control, communication error (data link error) is generated in the gateway unit.

Turn OFF communication switch (CN2SW) when changing the setting of controller (LEC) by connecting the teaching box (LEC-T1-□) of setting software (LEC-W2) to PC/TB connector (CN2). In this case, the communication from CC-Link to the controller (LEC) is cut.

## 4. Setting of controller (LEC)

Initial parameter setting is necessary for the controller (LEC) which is connected to the gateway unit. Set the following by directly connecting the teaching box (LEC-T1-□) or the setting software to the controller (LEC) before connecting the gateway unit.

Check the operation manual of the controller (LEC) and the teaching box (LEC-T1-□) when setting the controller (LEC).

### 4. 3. 1 ID setting

ID setting is necessary when connecting two or more controllers (LEC) to the gateway unit. Assign ID to each controller (LEC) in serial number so that the numbers do not overlap. The setting range of ID is between 1 to 12.

[Example of ID change procedure using the ACT Controller Setting software (LEC-W2)]

Start the setting software in Normal mode.

Open the parameter window.

Item	Value
Controller ID	9
IG pattern	0.4
ACC/DEC pattern	Trapezoid-motion
S-motion rate	0
Stroke(+)	1000.00
Stroke(-)	-1000.00
Max speed	100
Max ACC/DEC	2000
Def In position	0.10
ORIG offset	0.00
Max force	100
Para protect	1 : Common+StepData
Enable SW	Disable
Unit name	

### 4. 3. 2 Setting of the communication speed

It is necessary to match the gateway unit controller IF communication speed with the controller (LEC) communication speed. Set the controller IF communication speed at 115,2kbps to use the teaching box (LEC-T1-□)

[Communication speed change procedure Setting software (LEC-W2)]

Start the setting software with Normal mode.

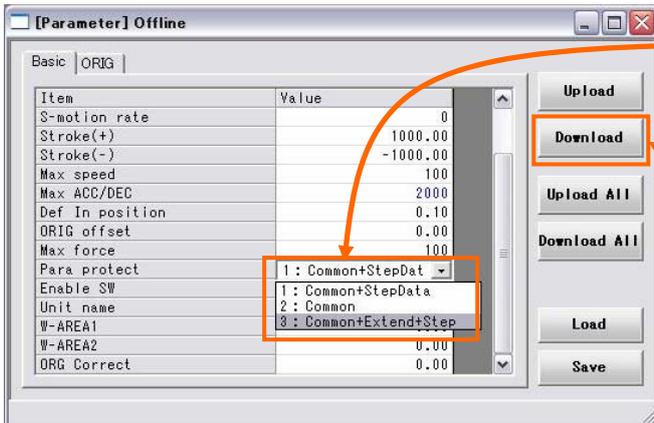
(1) Select [HELP] - [Password] from the menu. Password input screen below appears. Enter "password".



(2) Set the controller so that the communication speed can be changed.

Change "Parameter protect" setting so that "Communication speed" parameter can be changed.

View the parameters of the controller.



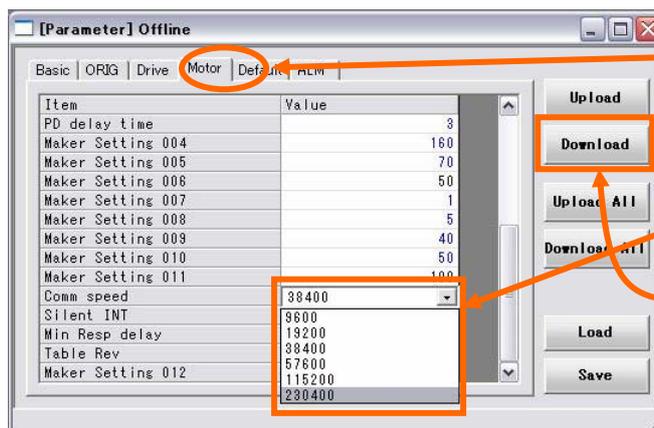
(2)-1 Change parameter protect to [3: Common + Extend + Step].

(2)-2 Select Download.

Select "Basic" Tab - Item "Parameter protect" to "3: Common + Extend + Step"

The changed data is sent by clicking the download button, and the parameter protect set value text changes from blue to black.

(3) Select the "Motor" Tab of the parameter window to change item "Comm speed" to "115200" for when using Teaching box or "230400" for when using ACT Controller software.



(3)-1 Select the tag "Motor".

(3)-2 Change the communication speed to 「115200」 (5) or 「230400」 (6)

(3)-3 Select Download.

The changed data is sent by clicking the download button, and "Communication speed" set value is changed from blue to black.

(4) Change item "Parameter protect" using "Basic" tab of the display of (2) to "1: Common + Step data" and click download.

(5) Close the ACT Controller software (LEC-W2) and turn OFF the controller (LEC) power supply. The changed communication speed will be valid from the next time the controller (LEC) is turned on.

### **Caution**

**The communication speed of the gateway unit and the controller (LEC) must match.**

If the communication speed does not match, the gateway unit and the controller (LEC) cannot communicate.

**Set the controller IF communication speed to 115,2kbps when using the teaching box (LEC-T1-)**

**The defaults setting of communication speed in the setting software (LEC-W2) is 38.6kbps.**

After changing the communication speed, set the ACT Controller software (LEC-W2) communication speed to 115.2kbps for Teaching box or 230.4kbps for the ACT controller software.

**Do not change any parameters other than "ID setting"/"Communication speed setting".**

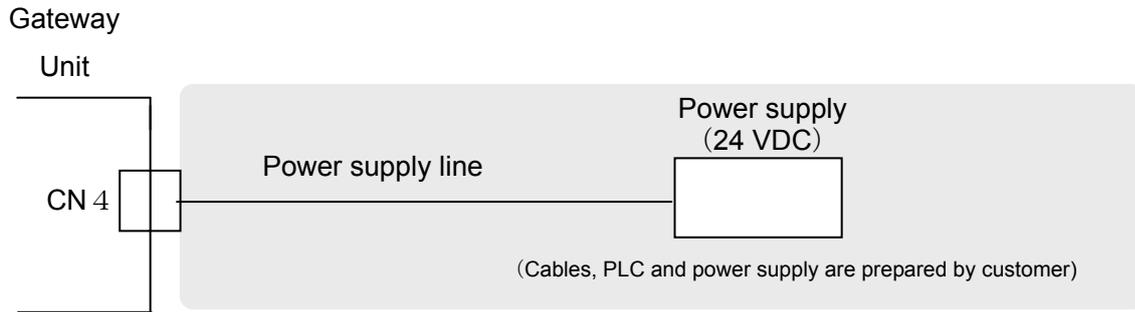
Otherwise, malfunction can result.

**Change "ID setting" / "Communication speed setting" to use the controller (LEC) stand-alone.**

## 5. External connection

### 5.1 CN4: Power supply connector

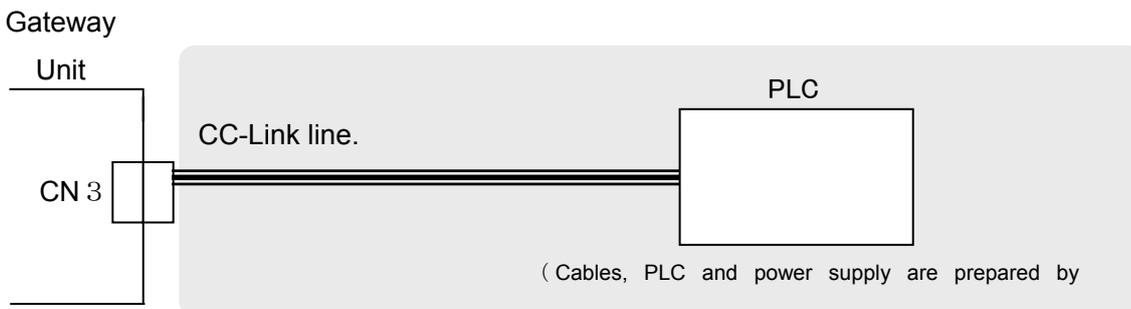
Connect the power supply. The gateway unit and the controller (LEC) should have the common 0V line.



\* Refer to **6. CN4: Power supply connector**

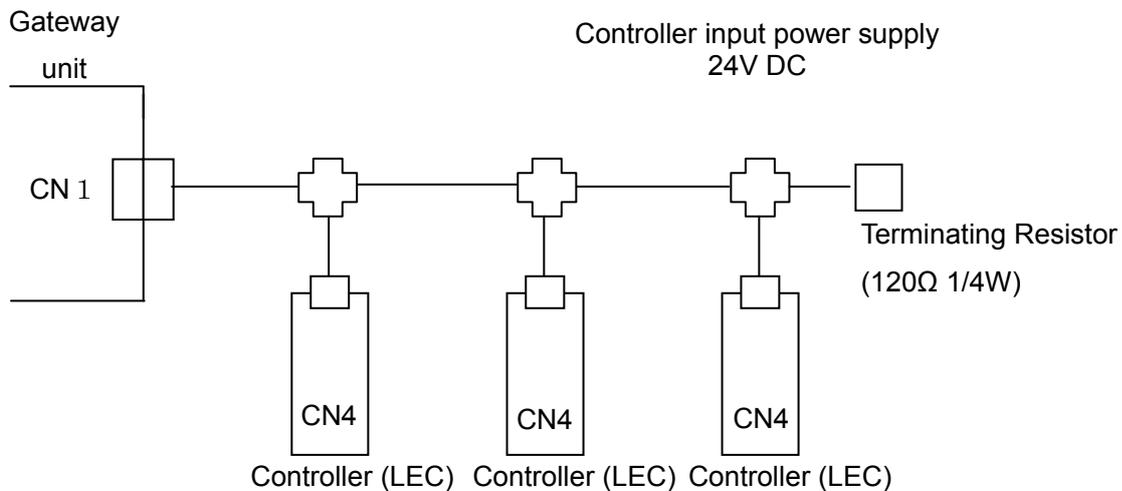
### 5.2 CN3: Bus connector

Connect the CC-Link line and the controller (LEC) with the communication cable (LEC-CG□-□).



### 5.3 CN1: CONT connector

Connect the gateway unit and the controller (LEC) to communication cable (LEC-CG□-□).



\* Refer to section **8. CN1: Controller IF communication connector(CONT)**

### **! Caution**

**Do not pull out the cable between the gateway unit and the cable, or cut off the power supply to the controller (LEC). Communication is interrupted.**

## **5. 4 CN2: PC/TB connector**

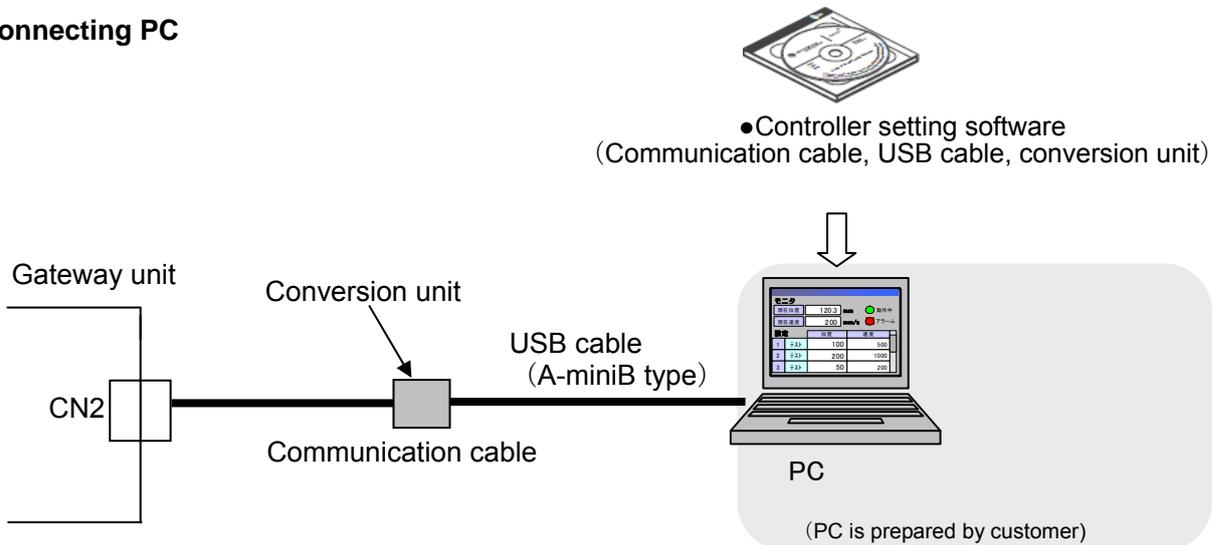
The connector which connects the tools teaching box (LEC-T1-3\*G\*) or PC (LEC-W2) for setting the controller (LEC).

The data link of the gateway unit and the controller (LEC) data is cut by turning off CN2SW or stopping data link, and communication with the tool teaching box (LEC-T1-3\*G\*) for setting the controller or PC (LEC-W2) becomes possible.

### **(1) Connecting the teaching box**



### **(2) Connecting PC**



※Refer to **8. CN2 : TB/PC Power supply connector(P.23)** for usage.

### **! Caution**

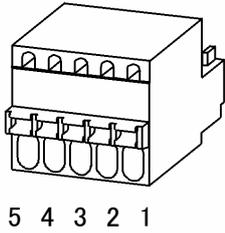
Do not start the setting software during data link.

Otherwise, communication error (data link error) is generated with the gateway unit.

## 6. CN4: Power supply connector

### 6.1 Power supply connector

Specifications of the communication connector in accessory



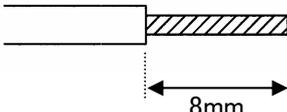
	terminal	Function	Functional explanation
1	EMG +	EMG signal output +	Output terminal of the emergency stop switch of the teaching box.
2	EMG -	EMG signal output -	
3	C 24V	Power supply + terminal	Power supply terminal of the Gateway unit (Power to the teaching box is supplied from this terminal)
4	0V	Power supply - Terminal	
5	FG	FG Terminal	Grounding terminal

### Caution

- (1) 0V line of the gateway unit and the motor controller (LEC) have to be common.
- (2) When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

### 6.2 Power line

(Power lines are prepared by customer. Specifications below need to be satisfied)

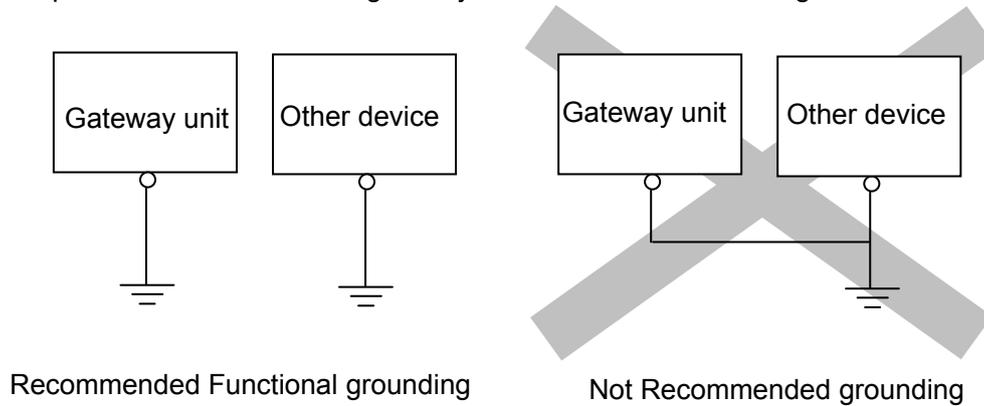
Item	Specifications	
Applicable wire Size	Power terminal (24V, 0V)	AWG20: Single line, No insulation sleeve, Twisted wire with bar terminal.  *The rated temperature for the insulation coating: 60 degrees C or more.
	EMG signal output (EMG+, EMG-)	AWG20: Single line, No insulation sleeve, Twisted wire with bar terminal.  *Rated temperature of the insulation cover is 60 degrees C or higher
Peeled wire length	 <p>The diagram shows a wire with a section of insulation removed. A double-headed arrow below the stripped section is labeled '8mm'.</p>	

### Caution

Do not connect multiple wires to one terminal.

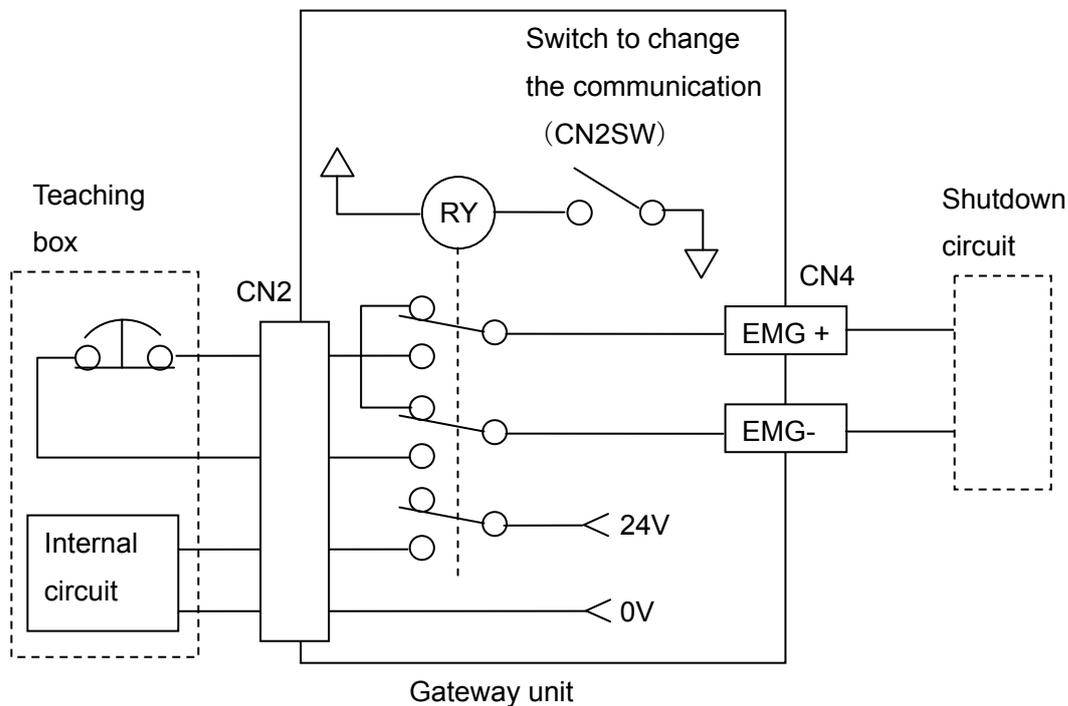
## ⚠ Caution

- (1) The earthing should be the dedicated grounding point. It should be a functional ground with less than 100  $\Omega$  resistance.
- (2) The ground point should be near this gateway unit to make the wire length shorter.



### 6.3 Wiring of the shutdown circuit

The gateway unit has terminals (EMG+, EMG-) which route the stop switch signal's from the teaching box when the communication switch (CN2SW) is turned on. Set the terminal to EMG terminal of the controller (LEC) when using the teaching box.



 **Caution**

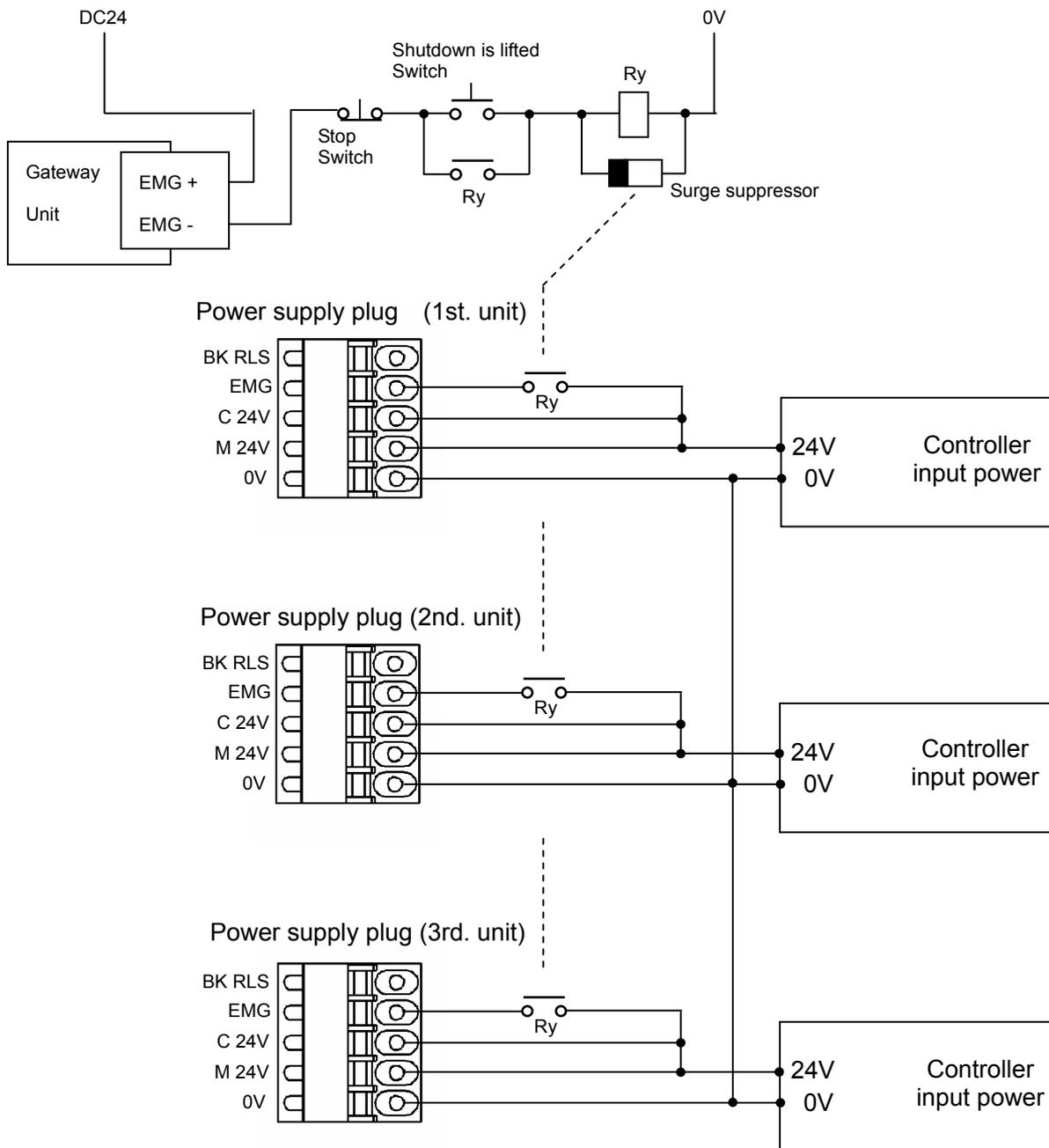
**Turn on the communication switch (CN2SW) before install / removal of the teaching box to / from the gateway unit.**

If EMG+ and EMG- terminals are connected to the controller (LEC) or a shutdown circuit and the communication switch is turned off when the teaching box is not connected, connected controller (LEC) or the shutdown circuit receives stop signal (Open between EMG+ and EMG-) and operation stops

### 【Shutdown circuit Example】

Shutdown circuit with gateway Check the circuit referring the controller (LEC) operation manual.

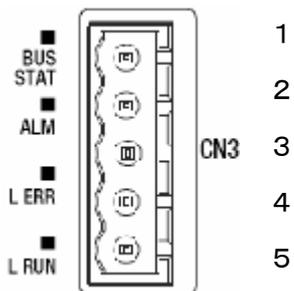
【Example of the circuit】 ex. LEC6



### **⚠ Caution**

When the stop signal is input, the controller (LEC) is stopped with max deceleration speed, and servo motor is turned off.

## 7. CN3: Bus conector



No	Designation	Description
1	DA	CC-Link communication line A
2	DB	CC-Link communication line B
3	DG	CC-Link ground line
4	SLD	CC-Link shield
5	FG	Frame ground

Connect the terminal resistance to the both ends of CC-Link main line.

CC-Link system has different terminal resistance to connect depending on used cables.

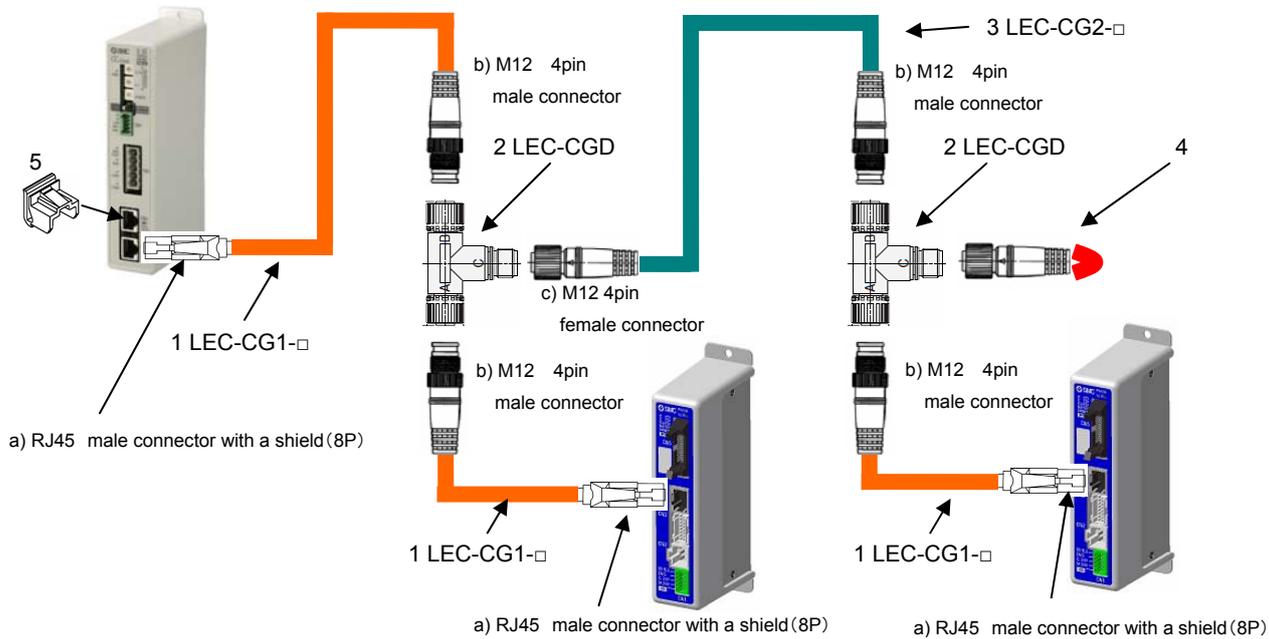
Type of cable	Resistance
Communication cable for CC-Link	110Ω 1/2W
CC-Link dedicated high-performance cable	120Ω 1/2W

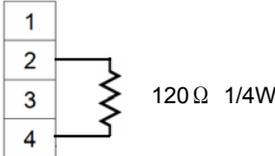
## 8. CN1: Controller IF communication connector (CONT)

### 8. 1 Connection

One unit can control up to 12 pcs. of controllers (LEC).

The example of link connection which consists of telecommunication cable LEC-CG 1-1 and cable LEC-CG 2-1 between branches is shown below.



No	Description	Part number	Content						
1	Communication cable cable	LEC-CG1-□ <table border="1"> <tr> <td>K</td> <td>0.3m</td> </tr> <tr> <td>L</td> <td>0.5m</td> </tr> <tr> <td>1</td> <td>1m</td> </tr> </table>	K	0.3m	L	0.5m	1	1m	Cable to connect the gateway unit CN1 and the branch connector, or controller (LEC) CN4 and the branch connector.
K	0.3m								
L	0.5m								
1	1m								
2	Branch connector	LEC-CGD	The junction cable to connect the gateway and the controller.						
3	Cable between branches	LEC-CG2-□ <table border="1"> <tr> <td>K</td> <td>0.3m</td> </tr> <tr> <td>L</td> <td>0.5m</td> </tr> <tr> <td>1</td> <td>1m</td> </tr> </table>	K	0.3m	L	0.5m	1	1m	Cable to connect the branch connector.
K	0.3m								
L	0.5m								
1	1m								
4	Terminating Resistor	-	Termination on RS-485 Bus (120 Ohms) Recommended connector :XS2C-D4** [OMRON Corporation] 						
5	RJ-45 connector dust cover	LEC-CAP-X22	Dust adhere when the RJ-45 connector is not connected with the CN1 or CN2 connector. Please attach a cover when you prevent the adhesion such as dust.						

Recommended connector

No	Description	Part number
a)	RJ45 male connector with a shield (8P)	TM21P-88P [HIROSE ELECTRIC CO., LTD.]
b)	M12 4pinmale connector	HR24-8DJ4PE550A(73) [HIROSE ELECTRIC CO., LTD.] XS2G-D4** [OMRON Corporation]
c)	M12 4pin female connector	HR24-8DP4S300(73) [HIROSE ELECTRIC CO., LTD.] XS2C-D4** [OMRON Corporation]

## 8. 2 Wiring diagram

For you reference, the example of wiring of the gateway unit CN1 is shown below.

The communication line from the gateway unit CN1 branches to each controller (LEC) by the branch connector. It is recommended to connect the terminating resistor (120Ω 1/4W) to the branch connector at the terminal.

When connecting the cable, the shield of the cable becomes same potential as 0V of the controller power supply.

When using it, do not contact it to conductive parts of switchboard, other instruments, wiring, etc.

← Gateway unit CN1

Description	Pin No.
N.C.	1
N.C.	2
SD+	3
SD-	4
N.C.	5
N.C.	6
N.C.	7
N.C.	8
Shield	

Branch

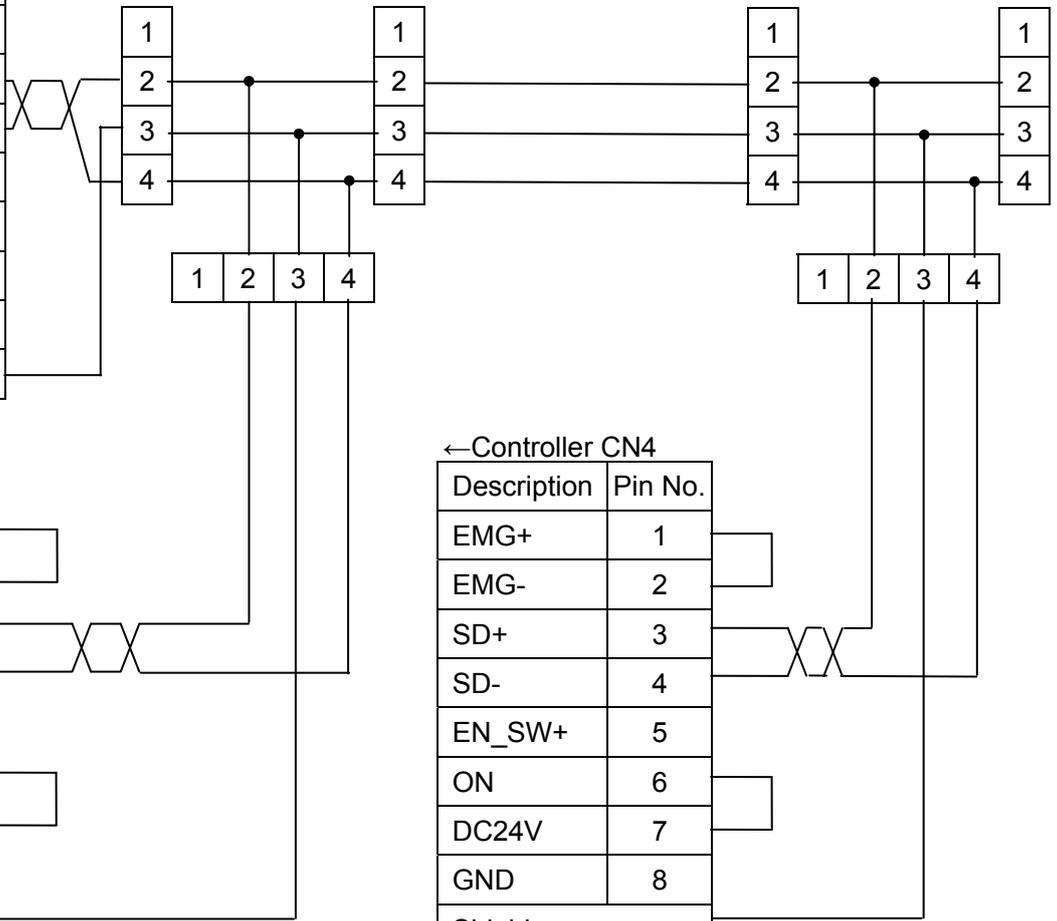
Branch

← Controller CN4

Description	Pin No.
EMG+	1
EMG-	2
SD+	3
SD-	4
EN_SW+	5
ON	6
DC24V	7
GND	8
Shield	

← Controller CN4

Description	Pin No.
EMG+	1
EMG-	2
SD+	3
SD-	4
EN_SW+	5
ON	6
DC24V	7
GND	8
Shield	



## 9. CN2: TB/PC connector

### 9. 1 How to use

This connector is for setting the controller (LEC) which is connected to the gateway unit by the teaching box or the set software.

When the communication switch (CN2SW) is turned off, the communication from CC-Link to the controller is disconnected, and the signal line of CN2 and CN1 is connected. From now on, the setting of each controller is possible.

The following is the setting procedure of the controller (LEC) when the teaching box or PC setting software is connected to the gateway unit.

#### 【Procedure to start setting】

- (1) Connect the teaching box or PC to CN2 of gateway unit.
- (2) Turn off the communication switch (CN2SW).
- (3) Reset signal is sent to all controllers (LEC) which are connected to the gateway unit, and the communication from CC Link to the controller (LEC) is disconnected. Reset signal stops all actuators.
- (4) Communication from the teaching box or PC becomes available.

#### 【Procedure to finish setting】

- (1) Finish the PC setting software.
- (2) Turn on the communication switch (CN2SW).  
(In case of the teaching box, power supply is turned off at this point)
- (3) Communication starts after the reset signal is sent from the gateway unit to the controller (LEC).  
Reset signal stops all the actuators immediately after communication starts.
- (4) Remove the teaching box or PC from the CN2 of gateway unit.

### Caution

**Do not start the setting software during data link (CN2SW turn on).**

Otherwise, communication error (data link error) is generated with the gateway unit.

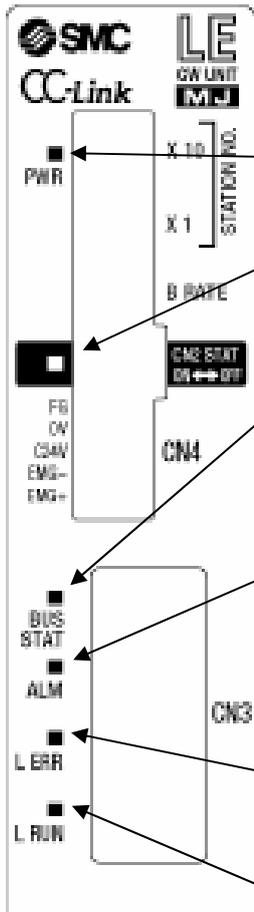
**Use the teaching box and the setting software after finishing startup process of the gateway unit (After ALM lamp green blinks). (CN2SW turn off etc.)**

The gateway unit communicates with controller (LEC) as startup processing immediately after turning on of the power supply.

At this time, if the teaching box or the setting software communicate to controller (LEC), communication error is generated.

# 10. LED display

## 10. 1 LED display



LED name	Content		
PWR	Power supply status is displayed	Off	Power is not supplied
		Green On	Power is supplied
CN2STAT	ON, OFF status of SN2SW	Off	When switch ON
		Green ON	When switch OFF
BUS STAT	Controller IF status	Green flashing	Communicating
		Off	Communication disconnected
ALM	The alarm status.	Green flashing	Normal status
		Orange flashing	Warning generated
		Red On	When alarm is generated or communication data link is disconnected.
L ERR	Error status (CC-Link)	Off	Normal status
		Red flashing	Warning generated
		Red On	Error generated
L RUN	Network status (CC-Link)	Off	Communication disconnected
		Green ON	Communicating

## 10. 2 Controller IF communication status and LED display

Gateway unit status		PWR	BUS STAT	ALM	CN2 STAT
Supply of power		Green On	Off	Off	Off
Controller (LEC) and normal communication		Green On	Green flashing	Green flashing	Off
Command to interrupt data link is being given		Green On	Off	Green flashing	Off
CN2SW OFF Command to interrupt data link is being given		Green On	Off	Green flashing	Green On
Controller IF	Communication error with some controllers (LEC) is detected.	Green On	Green flashing	Orange flashes	Off
	Communication error is detected for all controllers (LEC), or IF communication speed of the controller is incorrect.	Green On	Green flashing	Red On	Off

## 11. Mode

### 11. 1 Outline

This unit has 3 types of operation mode. These modes can be switched by mode change. Current mode can be checked by mode return

Refer to “12.4(1) Return of the mode” for “Return of the Mode”.

- Step data input mode

Operating actuator by using the memory of the gateway unit which corresponds to parallel IO of controller (LEC).

- Numerical data input mode

Operating actuator by using the memory of the gateway unit which corresponds to parallel IO of controller (LEC), and operating actuator by directly sending the parameters which like a position, a speed etc., are available.

- Step data writing mode

Operating actuator by using the memory of the gateway unit which corresponds to parallel IO of controller (LEC), and editing step data of the LEC□ controllers through the gateway unit, are available.

Please confirm the setting method of "Mode change" and "Mode return" by "Gateway control flag" and "Gateway unit state flag".

### 11. 2. Step data input mode

This is the mode that Operating actuator by using the memory of the gateway unit which corresponds to parallel IO of controller (LEC).

In case that “ID” setting of the controller(LEC) is “1”, the memory which corresponds to the parallel IO of controller can be operated by Rx80~Rx8F and Ry80~Ry8F.

Refer to the manual of controller (LEC) for detail of the function and the operation of parallel IO.

### 11. 3. Numerical data input mode

This is the mode that operating actuator by sending to controller (LEC) the data which is a position, a speed etc.

The actuator moves with the position, the speed etc which is specified by sent data.

In this mode, the command by using parallel I/O is available.

Before operating the actuator by directly sending the data which like a position, a speed etc, SVON and return to origin should be finished.

Please make same operation as performing SVON and return to origin with parallel IO by using the corresponding memory.

And operating the actuator is available by using the memory which corresponds to parallel IO of LEC controller.

Refer to the manual of controller (LEC) for detail of the function and the operation of parallel IO.

The data such as the current position can be read by “Setting numerical data”.

Refer to “12.4(5) Setting numerical data” for “Setting numerical data”.

● Operation commanded by Numerical data input mode (ID=1)

(1) Write "0" in RWwn [bit0-7].

(2) Write the motion profile (position, speed...) in RWwn [bit8-F] and RWwn+1 to 8.

Refer to "7.1 Step data" of the operation manual of the controller(LEC).

(3) Write "1" in RWwn [bit0-7]. Then, the command of the driving is sent to the controller (LEC).

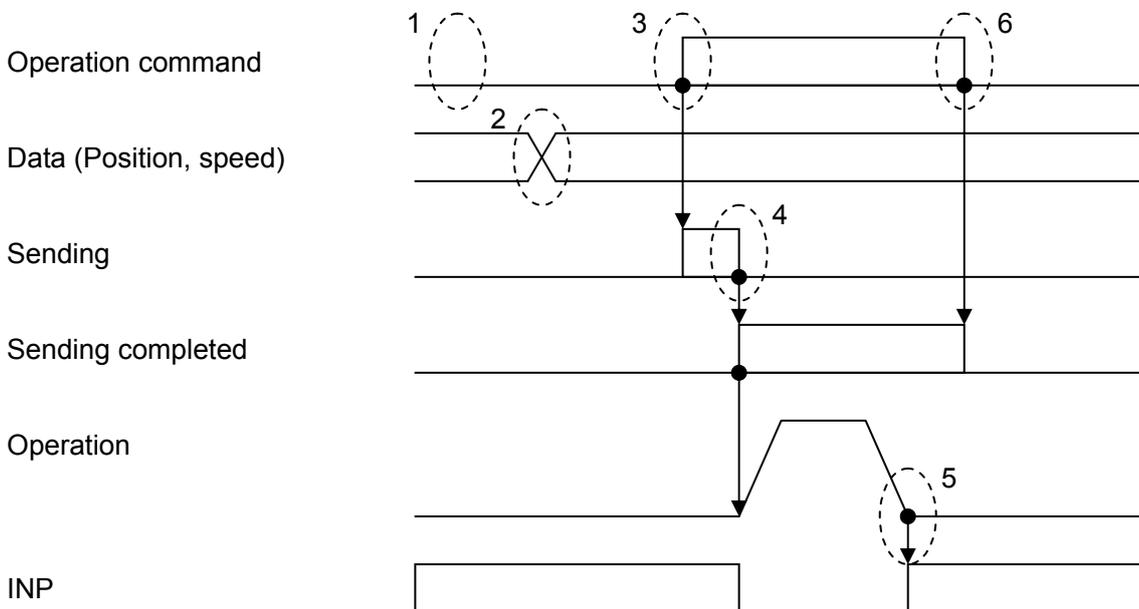
(4) When the sending to the controller(LEC) is completed, "Sending completed" (RWrn+8[bit 8]) changes from "0" to "1" and the actuator starts driving.

(5) And, when the actuator completes driving, "INP" (Rx8B) is changed from "0" to "1".

Refer to "6.3 Parallel IO input" of the operation manual of the controller(LEC) for detail of INP signal.

(6) Write "0" in RWwn [bit0-7].

Then, "Sending completed"(RWrn+8[bit 8]) is changed from "1" to "0".



## 11. 4. Data writing mode

This is the mode that the step data of the controller(LEC) can be changed through the gateway unit. After changing it, the changed step data is reflected by commanding to drive the changed step data. And the same functions as Step data input mode are available in this mode.

The driving and the return to origin etc. are commanded by using the memory which corresponds to parallel IO of LEC□ controller.

Refer to the manual of controller (LEC) for detail of the function and the operation of parallel IO.

### ●Writing step data method

(1)Write "0" in RWwn [bit8-F].

(2)Write the motion profile (position, speed...) in RWwn+1 to 8

Refer to "7.1 Step data" of the operation manual of the controller(LEC).

(3)Write the step data number which is changed in RWwn [bit0-7]. (Setting data range is from 0 to 63.)

(4)Write "1" in RWwn [bit8-F]. Then, the data which is written in avobe (2) are sent to the controller(LEC).

(5)When the sending to the controller(LEC) is completed, "Sending completed"(RWrn+8[bit 8]) is changed from "0" to "1".

(6)Write "0" in RWwn [bit8-F].

Then, "Sending completed " (RWrn+8[bit 8]) changes from "1" to "0".

## 12. Memory map

### 12. 1 Memory assignment

- Gateway unit --> Higher level device [IN] (Remote to Master)

Remote IO

Controller ID	Device No	Signal name
-	Rx00 to Rx2F	Modbus control flag
	Rx30 to Rx7F	Extended functionality
ID1	Rx80	OUT0
	Rx81	OUT1
	Rx82	OUT2
	Rx83	OUT3
	Rx84	OUT4
	Rx85	OUT5
	Rx86	-
	Rx87	-
	Rx88	BUSY
	Rx89	SVRE
	Rx8A	SETON
	Rx8B	INP
	Rx8C	AREA
	Rx8D	WAREA
	Rx8E	ESTOP
Rx8F	ALARM	
ID2	Rx90 to Rx9F	Same as ID1
ID3	RxA0 to RxAF	Same as ID1
ID4	RxB0 to RxBF	Same as ID1
ID5	RxC0 to RxCF	Same as ID1
ID6	RxD0 to RxDF	Same as ID1
ID7	RxE0 to RxEF	Same as ID1
ID8	RxF0 to RxFF	Same as ID1
ID9	Rx100 to Rx10F	Same as ID1
ID10	Rx110 to Rx11F	Same as ID1
ID11	Rx120 to Rx12F	Same as ID1
ID12	Rx130 to Rx13F	Same as ID1

•Please refer the operation manual of the step motor controller (LECP6) and the servo motor controller (LECA6) to check the detail of each signal.

Device No	Signal name
RX140~36F	Nouse
RX370	Nouse
RX371	
RX372	
RX373	
RX374	
RX375	
RX376	
RX377	
RX378	
RX379	Nouse
RX37A	Nouse
RX37B	Remote READY
RX37C	Nouse
RX37D	
RX37E	
RX37F	

•Initial data processing request flag

The initial data processing request flag is turned on after hardware is reset or after operating the test mode or after turning on the power supply to request initial data setting.

After complete the initial data processing, the initial data processing request flag is turned off. (After the initial processing completion flag (RY378) is turned on.)

•Remote READY

The remote READY is turned on when the initial data setting is completed after the power supply is turned on or after hardware is reset or after the test mode is operated and the state is READY.

The remote READY is used as interlock of reading/writing from the master unit. The remote READY is turned off in the test mode.

Remote Register

Corresponding ID	Address	Bit/Byte No.	Data name	Model /Size	Value range	Unit	Corresponding mode
ID1	RWrn	3	Current position	4	+/-2147483647	0.01mm	Numerical data input
		2					
	RWrn+1	1					
		0					
	RWrn+2	H	Current speed	2	0 to 65500	mm/s	
		L					
	RWrn+3	H	Current Force	2	0 to 300	%	
		L					
	RWrn+4	3	Target position	4	+/-2147483647	0.01mm	
		2					
	RWrn+5	1					
		0					
	RWrn+6	-	Alarm	4	0 to 255	-	
		-	Alarm				
RWrn+7	-	Alarm					
	-	Alarm					
RWrn+8	Controller IF status flag (ID=1)					All modes	
ID2	RWrn+9 to 17	Same as ID1					
ID3	RWrn+18 to 26	Same as ID1					
ID4	RWrn+27 to 35	Same as ID1					
ID5	RWrn+36 to 44	Same as ID1					
ID6	RWrn+45 to 53	Same as ID1					
ID7	RWrn+54 to 62	Same as ID1					
ID8	RWrn+63 to 71	Same as ID1					
ID9	RWrn+72 to 80	Same as ID1					
ID10	RWrn+81 to 89	Same as ID1					
ID11	RWrn+90 to 98	Same as ID1					
ID12	RWrn+99 to 107	Same as ID1					

- Higher level device --> Gateway unit [OUT] (Master to Remote)

Remote IO

Controller ID	Device No	Signal name
-	Ry00 to Ry2F	Modbus control flag
	Ry30 to Ry7F	Extended functionality
ID1	Ry80	IN0
	Ry81	IN1
	Ry82	IN2
	Ry83	IN3
	Ry84	IN4
	Ry85	IN5
	Ry86	- Please always turn OFF
	Ry87	- Please always turn OFF
	Ry88	HOLD
	Ry89	SON
	Ry8A	DRIVE
	Ry8B	RESET
	Ry8C	SETUP
	Ry8D	- Please always turn OFF
	Ry8E	- Please always turn OFF
	Ry8F	- Please always turn OFF
ID2	Ry90 to Ry9F	Same as ID1
ID3	RyA0 to RyAF	Same as ID1
ID4	RyB0 to RyBF	Same as ID1
ID5	RyC0 to RyCF	Same as ID1
ID6	RyD0 to RyDF	Same as ID1
ID7	RyE0 to RyEF	Same as ID1
ID8	RyF0 to RyFF	Same as ID1
ID9	Ry100 to Ry10F	Same as ID1
ID10	Ry110 to Ry11F	Same as ID1
ID11	Ry120 to Ry12F	Same as ID1
ID12	Ry130 to Ry13F	Same as ID1

•Please refer the operation manual of the step motor controller (LECP6) and the servo motor controller (LECA6) to check the detail of each signal.

Device No	Signal name
RY140~36F	Nouse
RY370	Nouse
RY371	
RY372	
RY373	
RY374	
RY375	
RY376	
RY377	
RY378	
RY379	Nouse
RY37A	Nouse
RY37B	Nouse
RY37C	
RY37D	
RY37E	
RY37F	

• Initial data setting complete flag

The initial data setting complete flag is turned on when the initial data process which is requested after the power supply is turned on or after hardware is reset or after the test mode is operated is completed.

Remote Register

Corresponding D	Address	Bit/Byte No.	Data name	Model/Size	Value range	Unit	Corresponding mode						
ID1	RWwn	-	Start flag	1	0: no send 1: send	-	Numerical data input						
			Step data No		0 to 63		Data writing						
	RWwn+1	H L	Speed	2	0 to 65500	mm/s	Numerical data input  Data writing						
			RWwn+2					3 2 1 0	Position	4	+/-2147483647	0.01mm	
	RWwn+3	H L		Acceleration	2	0 to 65500							mm/s <sup>2</sup>
				RWwn+4									
	RWwn+5	-	Pushing force		1	0 to 30		10%					
			RWwn+6	-					Trigger LV	1	0 to 30	10%	
	RWwn+7	-			Pushing speed	1		0 to 255	mm/s				
			RWwn+8	-	Positioning thrust					1	0 to 30	10%	
	RWwn+8	H L			In pos	2		0 to 65500	0.01mm				
			ID2	RWrn+9 to 17	Same as ID1								
	ID3	RWrn+18 to 26	Same as ID1										
	ID4	RWrn+27 to 35	Same as ID1										
ID5	RWrn+36 to 44	Same as ID1											
ID6	RWrn+45 to 53	Same as ID1											
ID7	RWrn+54 to 62	Same as ID1											
ID8	RWrn+63 to 71	Same as ID1											
ID9	RWrn+72 to 80	Same as ID1											
ID10	RWrn+81 to 89	Same as ID1											
ID11	RWrn+90 to 98	Same as ID1											
ID12	RWrn+99 to 107	Same as ID1											

Note) "0" is "no send" at mode of data writing. "1" and "2" contain "send" at mode of data writing.

### 12.1.1 Remote Register

8, 16, or 32 bit data is assigned to the remote register depending on the contents of the data.

#### **8 bit data**

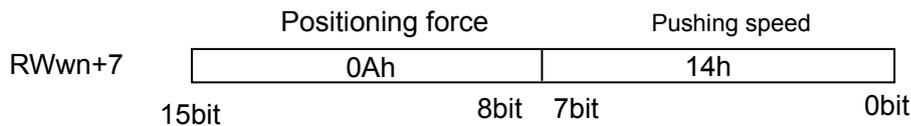
Please note the following for 8 bit data including pushing speed and positioning force.

Ex.) When inputting pushing speed of 20mm/s to RWwn+7 and 100% to positioning force.

Pushing speed 20mm/s is 14h in hexadecimal.

Positioning force data is expressed by 10%. The value to express 100% is 10, and 0Ah in hexadecimal.

If the data is input to the register, please do as following.



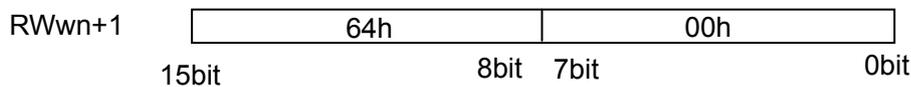
#### **16 bit data**

Please note followings for 16 bit data (WORD) including speed, acceleration, and deceleration .

Ex.) When inputting 100mm/s to speed (RWwn+1) .

100mm/s is 0064h in hexadecimal.

If 0064h is input to the register, please do as following.



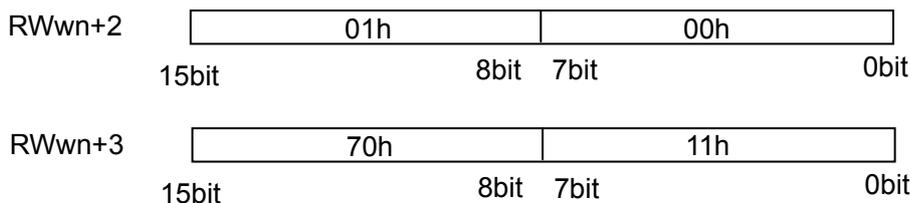
#### **32 bit data**

Please note followings for 32 bit data including position.

Ex.) When inputting 700.00mm to position (RWwn+2,3) .

Position is expressed by 0.01mm. The value to express 700.00mm is 70000, and 00011170h in hexadecimal.

When 00 01 11 70 h is input to the register, please do as following.



## 12. 2 Controller IF status flag

Controller IF flag is sent back to each ID ID=1 is shown below as an example

[ID=1]

I_Address \ bit	7	6	5	4	3	2	1	0
RWrn+8	—	—	—	—	—	—	Abnormal station	Connect station

I_Address \ bit	F	E	D	C	B	A	9	8
RWrn+8	—	—	—	—	—	—	Sending	Sending completed

### (1) Connect station

1 (ON) appears when it is confirmed that the motor controller (LEC) is connected. 0 (OFF) appears when the connection is not confirmed.

### (2) Abnormal station

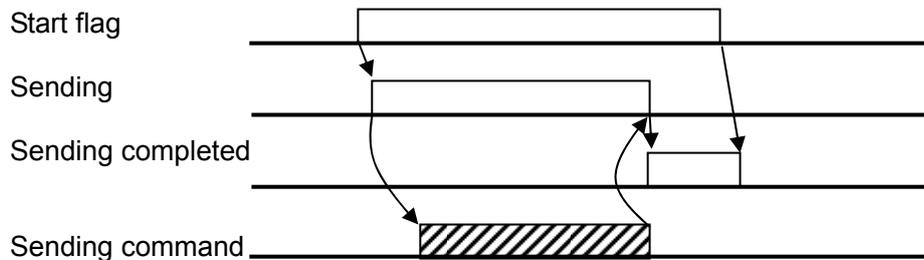
0 (OFF) appears when the communication with the motor controller is normal at the connect station. 1 (ON) appears when the communication is not normal.

### (3) Sending

1 (ON) appears while the operation command from the motor controller (LEC) is given and the sending of the operation data for the motor controller is completed at numerical data input mode. 0 (OFF) appears when the sending is completed.

### (4) Sending completed

1 (ON) appears when the sending of the operation command data to the motor controller (LEC) is completed at the numerical data input mode. 1 (ON) appears while the sending of the operation command data to the motor controller when the operation command is (ID=1).



## 12. 3 Gateway unit status flag

The flag to indicate the gateway communication status.

No	Signal name
Rx00	Return of the mode (L)
Rx01	Return of the mode (H)
Rx02	Nouse
Rx03	
Rx04	READY
Rx05	ALARM
Rx06	Initial
Rx07	During communication
Rx08	Return of the read numerical data (Valid only in numerical data input mode) (ID1)
Rx09	Return of the read numerical data (Valid only in numerical data input mode) (ID2)
Rx0A	Return of the read numerical data (Valid only in numerical data input mode) (ID3)
Rx0B	Return of the read numerical data (Valid only in numerical data input mode) (ID4)
Rx0C	Return of the read numerical data (Valid only in numerical data input mode) (ID5)
Rx0D	Return of the read numerical data (Valid only in numerical data input mode) (ID6)
Rx0E	Return of the read numerical data (Valid only in numerical data input mode) (ID7)
Rx0F	Return of the read numerical data (Valid only in numerical data input mode) (ID8)
Rx10	Return of the read numerical data (Valid only in numerical data input mode) (ID9)
Rx11	Return of the read numerical data (Valid only in numerical data input mode) (ID10)
Rx12	Return of the read numerical data (Valid only in numerical data input mode) (ID11)
Rx13	Return of the read numerical data (Valid only in numerical data input mode) (ID12)
Rx14	Nouse
Rx15	
Rx16	
Rx17	
Rx18	Return of the final station number (bit0)
Rx19	Return of the final station number (bit1)
Rx1A	Return of the final station number (bit2)
Rx1B	Return of the final station number (bit3)
Rx1C	Nouse
:	
Rx2F	

(1) Return of the mode  
Current mode is displayed

Rx01	Rx00	Mode name
0	0	Step data input mode
0	1	Numerical data input mode
1	0	Data writing mode

(2) READY

1 (ON) appears when the gateway is activated.

(3) ALARM

1 (ON) appears when one or more abnormal station are present, and the alarm is generated. 0 (OFF) appears when alarm is not generated.

(4) Initial

0 (OFF) appears during processing the initial for check the connect station. 1 (ON) appears when the processing of the initial is completed.

(5) During communication

1 (ON) appears when communication is made for one or more station. 0 (OFF) appears when not communicated.

In one of following cases, communication is not made.

CN2SW[Rx07] is ON.

Stop is ON.

All the connect stations become abnormal and the communication is stopped.

(6) Return of the read numerical data (Valid only in Numerical data input mode)

ON (1) appears in ID bit if numerical data can be read. OFF (0) appears when the data can not be read.

The command to read numerical data is given by "Setting numerical data".

Rx0F	Rx0E	Rx0D	Rx0C	Rx0B	Rx0A	Rx09	Rx08
ID8	ID7	ID6	ID5	ID4	ID3	ID2	ID1
-	-	-	-	Rx13	Rx12	Rx11	Rx10
-	-	-	-	ID12	ID11	ID10	ID9

(7) Return of the final station number

Return the range of the ID of the controller (LEC) to communication when the initial is processed. ID number is returned in binary digit.

ID	Rx1B	Rx1A	Rx19	Rx18
1	0	0	0	1
2	0	0	1	0
3	0	0	1	1
:	:			
12	1	1	0	0

## 12. 4 Gateway unit control flag

The flag to control the gateway communication status.

No	Signal name
Ry00	Mode command (L)
Ry01	Mode command (H)
Ry02	Nouse
Ry03	
Ry04	Reset
Ry05	Restart
Ry06	Nouse
Ry07	Stop
Ry08	Setting numerical data(Valid only in direct setting mode) (ID1)
Ry09	Setting numerical data(Valid only in direct setting mode) (ID2)
Ry0A	Setting numerical data(Valid only in direct setting mode) (ID3)
Ry0B	Setting numerical data(Valid only in direct setting mode) (ID4)
Ry0C	Setting numerical data(Valid only in direct setting mode) (ID5)
Ry0D	Setting numerical data(Valid only in direct setting mode) (ID6)
Ry0E	Setting numerical data(Valid only in direct setting mode) (ID7)
Ry0F	Setting numerical data(Valid only in direct setting mode) (ID8)
Ry10	Setting numerical data(Valid only in direct setting mode) (ID9)
Ry11	Setting numerical data(Valid only in direct setting mode) (ID10)
Ry12	Setting numerical data(Valid only in direct setting mode) (ID11)
Ry13	Setting numerical data(Valid only in direct setting mode) (ID12)
Ry14	Nouse
Ry15	
Ry16	
Ry17	
Ry18	Return of the final station number (bit0)
Ry19	Return of the final station number (bit1)
Ry1A	Return of the final station number (bit2)
Ry1B	Return of the final station number (bit3)
Ry1C	Nouse
:	
Ry2F	

(1) Mode command

Command the mode. Mode return is updated when the set mode becomes valid.

Ry01	Ry00	Mode name
0	0	Step data input mode
0	1	Numerical data input mode
1	0	Data writing mode

(2) Reset

Communication to the abnormal station restart when 0 (FF) is changed to 1 (ON). But, it is invalid when Stop is 1 (ON) or CN2SW is ON.

(3) Restart

Initial processing is executed again when 0 (OFF) is changed to 1 (ON). But, it is invalid when Stop is 1 (ON) or CN2SW is ON.

(4) Stop

All communications to the connected motor controller (LEC) are stopped when 0 (OFF) is changed to 1 (ON). Communication restart by changing to 0 (OFF) from 1 (ON).

(5) Setting numerical data(Valid only in direct setting mode)

ON (1) appears in ID bit if numerical data can be read. OFF (0) appears when the data can not be read.

Ry0F	Ry0E	Ry0D	Ry0C	Ry0B	Ry0A	Ry09	Ry08
ID8	ID7	ID6	ID5	ID4	ID3	ID2	ID1
-	-	-	-	Ry13	Ry12	Ry11	Ry10
-	-	-	-	ID12	ID11	ID10	ID9

(6) Return of the final station number

Indicates the range of the ID of the controller (LEC) to communication when the initial is processed. ID number is set in binary digit.

Input range is from 1 to 12. If the set value is lower than 0 or larger than 5, 5 is set.

ID	Rx1B	Rx1A	Rx19	Rx18
1	0	0	0	1
2	0	0	1	0
3	0	0	1	1
:	:			
12	1	1	0	0

## 13. Precautions for controlling the controller (LEC)

### 13. 1. Communication delay between the gateway unit unit and the controller(LEC)

There is communication delay between the gateway unit and the controller (LEC). Please refer to the procedure below for the control procedure taking the delay into consideration

For details of each signal, please refer to the operation manual of each motor controller (LEC) to be connected.

#### ●Example of operation indication with Step data input mode

	Command (Input signal)	⇒	Response (Output signal)	
(1)	DRIVE input ON (1)	⇒	Confirm that all OUT0 to 5 in the data information are changed to OFF (0) from values before DRIVE input ON (1).	
(2)	DRIVE input OFF (0)	⇒	Confirmed that OUT0 to 5 in the data information is the value within IN0 to 5 in specified data.	
(3)			INP is ON (1) and BUSY is OFF (0)	- Confirm the completion of the operation.

#### **Cautions for the above example**

When the operation is ordered right after the operation shown below, the response of DRIVE above are not recognized because OUT0 to 5 in the data information are all OFF (0) before turning ON (1) the DRIVE input. In this case, take measures against the communication delay by using the timer.

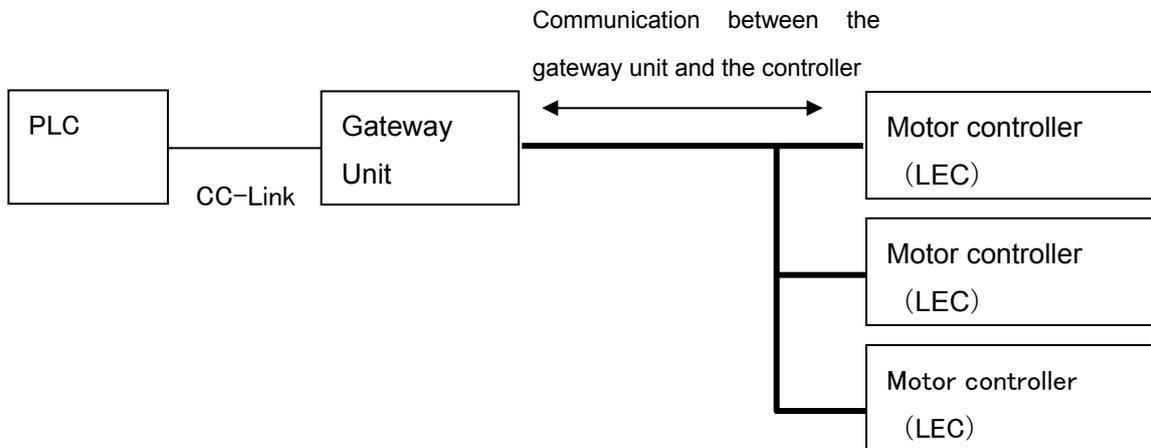
#### **【Condition in which OUT0 to 5 in the data information is all OFF】**

- Supply of power
- During and the right after the returning to origin position.
- RESET input ON
- After DRIVE input OFF(0) after commanding to start step data No.0

## 13. 2. Guideline of the Response delay between the Gateway and the Motor Control Unit

The gateway unit communicates with the motor controller (LEC) to read the controller status and commands the controller. The time for the communication causes delay in the response.

Please take this into consideration when selecting the PLC program.



### Communication to read the motor controller status

The gateway unit communicates one by one in order. The communication time is approximately 30ms per unit. When reading of numerical data is validated during Numerical data input mode or data rewrite mode, it takes another 30ms for communicating with valid controller (LEC).

### Communication for commanding the motor controller

When rewrite of the remote I/O and the register is commanded by CC-Link master, it takes 30ms for communicating with the target controller (LEC).

Response delay depends on the number of the connected motor controllers (LEC) and rewrite frequency.

Ex. 1) Response time guideline when four controllers are connected in step data input mode.

$$4 \text{ pcs.} \times \text{approx. } 30\text{ms} = \text{Approx. } 120\text{ms} + \alpha$$

[ $\alpha$  : Communication time to rewrite the remote I/O and the register]

Ex. 2) Response time guideline when twelve controllers are connected in step data input mode.

$$12 \text{ pcs.} \times \text{approx. } 30\text{ms} = \text{Approx. } 360\text{ms} + \alpha$$

[ $\alpha$  : Communication time to rewrite the remote I/O and the register]

Ex. 3) Response time guideline when 12 controllers are connected in numerical data input mode (6 controllers are valid for reading numerical data).

$$12 \text{ pcs.} \times \text{approx. } 30\text{ms} + 6\text{pcs.} \times \text{approx. } 30\text{ms} = \text{Approx. } 540\text{ms} + \alpha$$

[ $\alpha$  : Communication time to rewrite the remote I/O and the register]

※This response time does not include the response time of CC-Link and motor controller (LEC), and processing time of PLC.

## 14. Wiring of cables/Common precautions

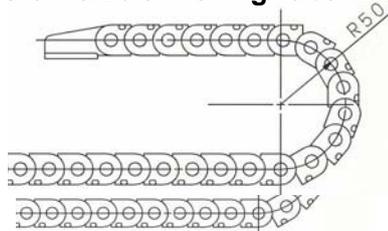
### Warning

- 1. Adjusting, mounting or wiring change should never be done before shutting off the power supply to the product.**  
Electrical shock, malfunction and damaged can result.
- 2. Never disassemble the cable. Use only specified cables.**
- 3. Never connect or disconnect the cable or connector with power on.**

### Caution

- 1. Wire the connector securely. Do not apply any voltage to the terminals other than those specified in the product Manual.**
- 2. Wire the connector securely.**  
Check for correct connector wiring and polarity.
- 3. Take appropriate measures against noise.**  
Noise in a signal line may cause malfunction. As a countermeasure, separate high voltage and low voltage cables, and shorten wiring lengths, etc.
- 4. Do not route wires and cables together with power or high voltage cables.**  
The product can malfunction due to interference of noise and surge voltage from power and high voltage cables to the signal line. Route the wires of the product separately from power or high voltage cables.
- 5. Take care that actuator movement does not catch cables.**
- 6. Operate with cables secured. Avoid bending cables at sharp angles where they enter the product.**
- 7. Avoid twisting, folding, rotating or applying an external force to the cable.**  
Risk of electric shock, wire break, contact failure and lost of control for the product can happen.
- 8. Fix the motor cable protruding from the product in place before using.**  
The motor and lock cables are not robotic type cables and can be damaged when moved. Therefore do not place it in a flexible moving tube.
- 9. The cable connecting the actuator and controller (LEC) is superior in bending resistance, but should not be placed into a flexible moving tube with a radius smaller than the specified value.**

( Min. 50 mm)



- 10. Confirm proper wiring of the product.**  
Poor insulation (interference with other circuits, poor insulation between terminals and etc.) can apply excessive voltage or current to the product causing damage.
- 11. The Speed / pushing force may vary, depending on the cable length, load and mounting conditions etc..**  
If the cable length exceeds 5m, the speed / pushing force will be reduced by a maximum of 10% per 5m. (If cable length is 15m: Maximum 20% reduction.)

### [Transportation]

### Caution

- 1. Do not carry or swing the product by the motor or the cable**

## 15. Electric actuators/Common precautions

### 15.1 Design and selection

#### Warning

**1. Be sure to read the Operation Manual.**

Handling or usage/operation other than that specified in the Operation Manual may lead to breakage and operation failure of the product.

Any damage attributed to the use beyond the specifications is not guaranteed.

**2. There is a possibility of dangerous sudden action by the product if sliding parts of machinery are twisted due to external forces, etc.**

In such cases, human injury may occur, such as by catching hands or feet in the machinery, or damage to the machinery itself may occur. Design the machinery should be designed to avoid such dangers.

**3. A protective cover is recommended to minimize the risk of personal injury.**

If a driven object and moving parts of the product are in close proximity, personal injury may occur. Design the system to avoid contact with the human body.

**4. Securely tighten all stationary parts and connected parts so that they will not become loose.**

When the product operates with high frequency or is installed where there is a lot of vibration, ensure that all parts remain secure.

**5. Consider a possible loss of power source.**

Take measures to prevent injury and equipment damage even in the case of a power source failure.

**6. Consider behavior of emergency stop of whole system.**

Design the system so that human injury and/or damage to machinery and equipment will not be caused, when it is stopped by a safety device for abnormal conditions such as a power outage or a manual emergency stop of whole system.

**7. Consider the action when operation is restarted after an emergency stop or abnormal stop of whole system.**

Design the system so that human injury or equipment damage will not occur upon restart of operation of whole system.

**8. Disassembly and modification prohibited**

Do not modify or reconstruct (including additional machining) the product. An injury or failure can result.

**9. Do not use stop signal, "EMG" of the controller and stop switch on the teaching box as the emergency stop of system.**

The stop signal, "EMG" of controller and the stop switch on the teaching box are for decelerating and stopping the actuator.

Design the system with an emergency stop circuit which is applied relevant safety standard separately.

**10. When using it for vertical application, it is necessary to build in a safety device.**

The rod may fall due to the weight of work. The safety device should not interfere with normal operation of the machine.

#### Caution

**1. Operate within the limits of the maximum usable stroke.**

The product will be damaged if it is used with the stroke which is over the maximum stroke. Refer to the specifications of the product.

**2. When the product repeatedly cycles with partial strokes, operate it at a full stroke at least once a day or every 1000 strokes.**

Otherwise, lubrication can run out.

3. **Do not use the product in applications where excessive external force or impact force is applied to it.**  
The product can be damaged. Each component that includes motor is made with accurate tolerance. So even slightly deformed or miss-alignment of component may lead operation failure of the product.
4. **Refer to a common auto switch /matter (Best Pneumatics No 2) when an auto switch is built in and used.**
5. **Return to origin cannot return while operating.**  
It cannot be done during positioning operation, pushing operation and pushing.
6. **When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.**

## 15.2 Mounting

### Warning

1. **Install and operate the product only after reading the Operation Manual carefully and understanding its contents. Keep the manual in a safe place future reference.**
2. **Observe the tightening torque for screws.**  
Tighten the screws to the recommended torque for mounting the product.
3. **Do not make any alterations to this product.**  
Alterations made to this product may lead to a loss of durability and damage to the product, which can lead to human injury and damage to other equipment and machinery.
4. **When using external guide, the guide axis should be parallel to the actuator axis.**  
There will be damage/excessive wear on the lead screw if the external guide is not parallel.
5. **When an external guide is used, connect the moving parts of the product and the load in such a way that there is no interference at any point within the stroke.**  
Do not scratch or dent the sliding parts of the product tube or piston rod etc., by striking or grasping them with other objects. Components are manufactured to precise tolerances, so that even a slight deformation may cause faulty operation.
6. **Prevent the seizure of rotating parts.**  
Prevent the seizure of rotating parts (pins, etc.) by applying grease.
7. **Do not use the product until you verify that the equipment can be operated properly.**  
After mounting or repair, connect the power supply to the product and perform appropriate functional inspections to check it is mounted properly.
8. **At the overhang mounted impeller fixation**  
There is a possibility that the power at the bending moment damages the actuator when moving it at high speed.  
The support metal fittings that suppress the vibration of the main body of the actuator are installed. Lower and use speed for the state that the actuator doesn't vibrate.
9. **When attaching work piece, do not apply strong impact or large moment.**  
If an external force over the allowable moment is applied, it may cause looseness in the guide unit, an increase in sliding resistance or other problems.
10. **Maintenance space.**  
Allow sufficient space for maintenance and inspection.

## 15.3 Handling

### Warning

**1. Do not touch the motor while in operation.**

The surface temperature of the motor can increase to approx. 90oC to 100oC due to operating conditions. Energizing alone may also cause this temperature increase. As it may cause burns, do not touch the motor when in operation.

**2. If abnormal heating, smoking or fire, etc., occurs in the product, immediately shut off the power supply.**

**3. Immediately stop operation if abnormal operation noise or vibration occurs.**

If abnormal operation noise or vibration occurs, the product may have been mounted incorrectly. Unless operation of the product is stopped for inspection, the product can be seriously damaged.

**4. Never touch the rotating part of the motor or moving part of the actuator while in operation.**

**5. When installing, adjusting, inspecting or performing maintenance on the product, controller and related equipment, be sure to shut off the power supply to each of them. Then, lock it so that no one other than the person working can turn the power on, or implement measures such as a safety plug.**

**6. In the case of the actuator that has a servo motor (24VDC), the “motor phase detection step” is done by inputting the servo on signal just after the controller power is turned on. The “motor phase detection step” operates the table/rod to the maximum distance of the lead screw. (The motor rotates in the reverse direction if the table hits an obstacle such as the end stop damper.) Take the “motor phase detection step” into consideration for the installation and operation of this actuator.**

### Caution

**1. Keep the controller and product combined as delivered for use.**

The product is set in parameters for shipment. If it is combined with a different parameter, failure can result.

**2. Check the product for the following points before operation.**

- a) Damage to electric driving line and signal lines
- b) Looseness of the connector to each power line and signal line
- c) Looseness of the actuator/cylinder and controller/driver mounting
- d) Abnormal operation
- e) Emergency stop of the total system

**3. When more than one person is performing work, decide on the procedures, signals, measures and resolution for abnormal conditions before beginning the work. Also, designate a person to supervise work other than those performing work.**

**4. Actual speed of the product will be changed by the workload.**

Before selecting a product, check the catalog for the instructions regarding selection and specifications.

**5. Do not apply a load, impact or resistance in addition to a transferred load during return to origin.**

In the case of the return to origin by pushing force, additional force will cause displacement of the origin position since it is based on detected motor torque.

**6. Do not remove the name plate.**

**7. Operation test should be done by low speed. Start operation by predefined speed after confirming there is no trouble.**

### [Earth]

#### Warning

**1. Please give the earth of the actuator.**

**2. Please make it to the earth of the exclusive use. The earth construction is D seed.**  
(Below earth resistance 100Ω)

**3. Please shorten the distance until the actuator and earth.**

## [Unpackaging]

### Caution

**1. Check the received product is as ordered.**

If a different product is installed from the one ordered, injury or damage can result.

## 15.4 Operating environment

### Warning

**1. Avoid use in the following environments.**

- a. Locations where a large amount of dusts and cutting chips are airborne.
- b. Locations where the ambient temperature is outside the range of the temperature specification (refer to specifications).
- c. Locations where the ambient humidity is outside the range of the humidity specification (refer to specifications).
- d. Locations where corrosive gas, flammable gas, sea water, water and steam are present.
- e. Locations where strong magnetic or electric fields are generated.
- f. Locations where direct vibration or impact is applied to the product.
- g. Areas that are dusty, or are exposed to splashes of water and oil drops.
- h. Areas exposed to direct sunlight (ultraviolet ray).

**2. Do not use in an environment where the product is directly exposed to liquid, such as cutting oils.**

If cutting oils, coolant or oil mist contaminates the product, failure or increased sliding resistance can result.

**3. Install a protective cover when the product is used in an environment directly exposed to foreign matters such as dust, cutting chips and spatter.**

Play or increased sliding resistance can result.

**4. Shade the sunlight in the place where the product is applied with direct sunshine.**

**5. Shield the valve from radiated heat generated by nearby heat sources.**

When there is a heat source surrounding the product, the radiated heat from the heat source can increase the temperature of the product beyond the operating temperature range. Protect it with a cover, etc.

**6. Grease oil can be decreased due to external environment and operating conditions, and it deteriorates lubrication performance to shorten the life of the product.**

## [Storage]

### Warning

- 1. Do not store the product in a place in direct contact with rain or water drops or is exposed to harmful gas or liquid.**
- 2. Store in an area that is shaded from direct sunlight and has a temperature and humidity within the specified range (-10oC to 60oC and 35 to 85% No condensation or freezing.**
- 3. Do not apply vibration and impact to the product during storage.**

## 15.5 Maintenance

### Warning

1. **Do not disassemble or repair the product.**

Fire or electric shock can result.

2. **Before modifying or checking the wiring, the voltage should be checked with a tester 5 minutes after the power supply is turned off.**

Electrical shock can result.

### Caution

1. **Maintenance should be performed according to the procedure indicated in the Operating Manual.**

Incorrect handling can cause injury, damage or malfunction of equipment and machinery.

2. **Removal of product.**

When equipment is serviced, first confirm that measures are in place to prevent dropping of work pieces and run-away of equipment, etc, and then cut the power supply to the system. When machinery is restarted, check that operation is normal with actuators in the proper positions.

## [Lubrication]

### Caution

1. **The product has been lubricated for life at manufacturer, and does not require lubrication in service.**

Contact SMC if lubrication will be applied.

## 15.6 Precautions for actuator with lock

### Warning

1. **Do not use the lock as a safety lock or a control that requires a locking force.**

The lock used for the product with a lock is designed to prevent dropping of work piece.

2. **For vertical mounting, use the product with a lock.**

If the product is not equipped with a lock, the product will move and drop the work piece when the power is removed.

3. **"Measures against drops" means preventing a work piece from dropping due to its weight when the product operation is stopped and the power supply is turned off.**

4. **Do not apply an impact load or strong vibration while the lock is activated.**

If an external impact load or strong vibration is applied to the product, the lock will lose its holding force and damage to the sliding part of the lock or reduced lifetime can result. The same situations will happen when the lock slips due to a force over the thrust of the product, as this accelerates the wear to the lock.

5. **Do not apply liquid or oil and grease to the lock or its surrounding.**

When liquid or oil and grease is applied to the sliding part of the lock, its holding force will reduce significantly.

6. **Take measures against drops and check that safety is assured before mounting, adjustment and inspection of the product.**

If the lock is released with the product mounted vertically, a work piece can drop due to its weight.

## 16. Gateway unit and its peripheral devices /Specific product precautions

### 16.1 Design and selection

#### Warning

**1. Be sure to apply the specified voltage.**

Otherwise, a malfunction and breakage of the gateway unit may be caused.

If the applied voltage is lower than the specified, it is possible that the load cannot be moved due to an internal voltage drop. Please check the operating voltage before use.

**2. Do not operate beyond the specifications.**

It may cause a fire, malfunction or actuator damage can result. Please check the specifications before use.

**3. Install an emergency stop circuit.**

Please install an emergency stop outside of the enclosure so that it can stop the system operation immediately and intercept the power supply.

**4. In order to prevent danger and damage due to the breakdown and the malfunction of this product, which may occur at a certain probability, a backup system should be established previously by giving a multiple-layered structure or a fail-safe design to the equipment, etc.**

**5. If a fire or danger against the personnel is expected due to an abnormal heat generation, ignition, smoking of the product, etc., cut off the power supply for this product and the system immediately.**

**6. Use UL1310 compliant Class 2 power supply unit for direct current.**

### 16.2 Handling

#### Warning

**1. The inside of the gateway unit and its connector should not be touched.**

It may cause an electric shock or damage to the controller.

**2. Do not perform the operation or setting of this equipment with wet hands.**

It may cause an electric shock.

**3. Product with damage or the one lacking of any components should not be used.**

It may cause an electric shock, fire, or injury.

**4. Use only the specified combination between the controller and electric actuator.**

It may cause damage to the controller or the actuator.

**5. Be careful not to be caught or hit by the workpiece while the actuator is moving.**

It may cause an injury.

**6. Do not connect the power supply or power on the product before confirming the area where the work moves is safe.**

The movement of the work may cause accident.

**7. Do not touch the product when it is energized and for some time after power has been disconnected, as it is very hot.**

It may lead to a burn due to the high temperature.

**8. Check the voltage using a tester for more than 5 minute after power-off in case of installation, wiring and maintenance.**

There is a possibility of getting electric shock, fire and injury.

9. **Do not use in an area where dust, powder dust, water or oil is in the air.**  
It will cause failure or malfunction.
10. **Do not use in an area where a magnetic field is generated.**  
It will cause failure or malfunction.
11. **Do not install in the environment of flammable gas, corrosive gas and explosive gas.**  
It could lead to fire, explosion and corrosion.
12. **Radiant heat from strong heat supplies such as a furnace, direct sunlight, etc. should not be applied to the product.**  
It will cause failure of the gateway unit or its peripheral devices.
13. **Do not use the product in an environment subject to a temperature cycle.**  
It will cause failure of the gateway unit or its peripheral devices.
14. **Do not use in a place where surges are generated.**  
When there are units that generate a large amount of surge around the product (e.g., solenoid type lifters, high frequency induction furnaces, motors, etc.), this may cause deterioration or damage to the product's internal circuit. Avoid supplies of surge generation and crossed lines.
15. **The product is not immune to lightning strikes. Take measures against lightning strikes in the system.**
16. **Do not install this product in an environment under the effect of vibrations and impacts.**  
It will cause failure or malfunction.
17. **If this product is used with a relay or solenoid valve, they should be the surge absorbing element built-in type.**

### 16.3 Mounting

#### Warning

1. **The gateway unit and its peripheral devices should be installed on a fire-proof material.**  
A direct installation on or near a flammable material may cause fire.
2. **Do not install this product in a place subject to vibrations and impacts.**  
It may cause an electric shock, fire, or injury.
3. **Take measure so that the operating temperature of this gateway unit and its peripheral devices are within the range of the specifications. Also, this controller should be installed with 50mm or larger spaces between each side of it and the other structures or components.**  
It may cause a malfunction of the controller and its peripheral devices and a fire.
4. **Do not mount this gateway unit and its peripheral devices together with a large-sized electromagnetic contactor or no-fuse breaker, which generates vibration, on the same panel. Mount them on different panels, or keep the controller and its peripheral devices away from such a vibration supply.**
5. **This gateway unit and its peripheral devices should be installed on a flat surface.**  
If the mounting surface is distorted or not flat, an unacceptable force may be added to the housing, etc. to cause troubles.

## 16.4 Electrical wiring

### Warning

- 1. Do not apply any excessive force to cables by repeated bending, tensioning or placing a heavy object on the cables.**  
It may cause an electric shock, fire, or breaking of wire.
- 2. Connect wires and cables correctly.**  
Incorrect wiring could break the gateway unit or its peripheral devices depending on the seriousness.
- 3. Do not connect wires while the power is supplied.**  
It can break the gateway unit or its peripheral devices could be damaged to cause a malfunction.
- 4. Do not carry this product by holding its cables.**  
It may cause an injury or damage to the product.
- 5. Do not connect power cable or high-voltage cable in the same wiring route as the unit.**  
The wires to the gateway unit or its peripheral devices can be interrupted with noise or induced surge voltage from power lines or high-voltage lines and malfunction could be caused.  
Separate the wiring of the gateway unit and its peripheral device from that of power line and high voltage line.
- 6. Verify the insulation of wiring.**  
Insulation failure (interference with other circuit, poor insulation between terminals and etc.) could introduce excessive voltage or current to the gateway unit or its peripheral devices and damage them.

## 16.5 Power supply

### Caution

- 1. Use a power supply that has low noise between lines and between power and ground.**  
In cases where noise is high, an isolation transformer should be used.
- 2. To prevent surges from lightning, an appropriate measure should be taken. Ground the surge absorber for lightning separately from the grounding of the gateway unit and its peripheral devices.**

## 16.6 Grounding

### Warning

- 1. Be sure to carry out grounding in order to ensure the noise tolerance of the gateway unit.**  
It may cause an electric shock or fire.
- 2. Dedicated grounding should be used.**  
Grounding should be to a D-class ground (Ground resistance of 100  $\Omega$  or less.)
- 3. Grounding should be performed near the unit as much as possible to shorten the grounding distance.**
- 4. In the unlikely event that malfunction is caused by the ground, it may be disconnected.**

## 16.7 Maintenance

### Warning

**1. Perform a maintenance check periodically**

Confirm wiring and screws are not loose.

Loose screws or wires may cause unintentional malfunction.

**2. Conduct an appropriate functional inspection after completing the maintenance.**

In case of any abnormalities (in the case that the actuator does not move, etc.), stop the operation of the system. Otherwise, an unexpected malfunction may occur and it will become impossible to secure the safety.

**3. Do not disassemble, modify or repair this gateway unit and the peripheral equipment.**

**4. Do not put anything conductive or flammable inside of this gateway unit.**

It may cause a fire and explosion.

**5. Do not conduct an insulation resistance test and withstand voltage test on this product.**

**6. Ensure sufficient space for maintenance activities. Provide space required for maintenance.**

Design the system that allows required space for maintenance.

**7. Do not use solvents such as benzene, thinner etc. to clean the gateway unit.**

They could damage the surface of the body and erase the markings on the body.

Use a soft cloth to remove stains.

For heavy stains, use a cloth soaked with diluted neutral detergent and fully squeezed, then wipe up the stains again with a dry cloth.

#### Revision history

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No.LEC-OM03402 Mar/2012 Revision
No.LEC-OM03803 Apr/2012 Revision Addition to notes about UL recognition

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Note: Specifications are subject to change without prior notice and any obligation on the part of the manufacturer.

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